# MULTI AXIS DRIVES



Rev. A, April 2024

## COMPACT MULTI AXIS SERVO DRIVE

WHEN PERFORMANCE REALLY MATTERS



If you need the best performance and design flexibility, look no further than Moog and its expertise. Based on our partnership, creativity and cutting-edge technological solutions, we can help you tackle the toughest problems and improve the performance of your machines.

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## MAKING THE IMPOSSIBLE POSSIBLE IN MOTION CONTROL

Moog Industrial is your partner of choice when performance really matters. We combine world class technologies with expert advisory support to solve our customers' most difficult challenges in motion control.

#### **Our Experience**

Moog Industrial excels in a wide range of applications, including industrial automation, machine building, robotics and medical motion control - just to name a few.

Get exceptional customer support from our well-trained experts, backed by Moog's longstanding track record of high performance and trusted experience. All related technology is owned by Moog.

#### Will Make You Triumph

Moog's typical hands-on mentality and our ambition to make the impossible possible in motion control can provide you with a competitive advantage, which will most likely last for years.

Our formula:

- Superior and reliable machine design, based on technology-neutral approach
- Customize to your very specific requirements, including the utmost compactness and quietness
- Improved profitability through economically effective project design
- A trustful partnership, driven by empathy and passion









## SYSTEM OVERVIEW

#### Flexible, modular design for top productivity

- The DM2020 is a compact, digital drive controlling top-performing multi-axis systems.
- The modular platform, high performance control card and advanced control software all help to improve performance levels in a wide range of industrial applications requiring optimum dynamics and precision, and where greater efficiency in terms of energy conversion and system integration means an essential plus factor for the new markets. These markets include electric and hybrid propulsion, and the conversion of general mechanical energy into electrical energy.
- The flexible design (based on "functional blocks") and the support of our engineers when it comes to machine design, means we can personalize the product to match our customers' needs, improving machine performance and reducing overall costs.

# A compact design, to reduce space and cut wiring costs

- The multi-axis architecture, with a shared power supply unit, reduces the dimensions of the axis module and the overall system dimensions by about 50% compared with a similar stand-alone configuration. The auxiliary power supplies between each axis are distributed by means of internal connections.
- The electrical connections in the system (via bus bar) reduce the wiring complexity and the number of components around the housing (switches, filters, counters and in-line inductors).

# Designed to work with different motor types and feedback devices

• The system manages a wide range of controlled motors (brushless and asynchronous) and accepted transducers - Resolver (any number of poles can be configured via the SW) or Encoder (incremental, sinusoidal, single and multi-turn or fully digital) - to meet all application requirements.

#### **Energy savings**

• The configuration with shared DC BUS allows an exchange of energy between the axes, reducing both energy waste from the dynamic brake resistor and the system's total energy consumption.

#### User-friendly graphic user interface (GUI)

- The new graphic user interface offers easy access to all the functions, simplifying the settings, initial start-up and system monitoring.
- The high frequency data registration and system identification functions, together with the assisted calibration function, make it easier to configure even the most complex systems.

#### Maximum synchronization between the axes

 The dual-axis layout implemented in a single module, plus the connection between different modules (via CANopen), is essential to improve the synchronization between high performance axes; this in turn is fundamental for improving configurations such as Primary/Secondary, bridge (gantry) crane, and electrical energy conversion lines.

#### **Customized applications**

- Applications controlling multi-axis systems in industrial automation.
- Applications with high precision and the maximum dynamics.
- Applications for energy savings.
- Applications with customized functions.
- Applications requiring quick, precise synchronization between the axes.
- Energy conversion (from mechanical to electrical and vice versa), where performance, efficiency and excellent integration are needed.

Note: The DM2020 drives aren't included in the list of "dual use" products, as defined in the framework regulation EC 428/2009, and are therefore not subject to its restrictions regarding sale and transportation.

#### **INTRODUCTION**



#### Configuration description:

The figure shows an example of a 12-axis system consisting of, from the left, a 50mm power supply unit, 2 size l100 modules, 2 size l75 modules, and 2 size l50 modules. All the modules have double axes.

## CHARACTERISTICS

#### Characteristics of the axis module

- The dimensions of the standard module, with a height and depth (455 mm/10.04 inches and 249 mm/9.80 inches) are the same for all modules; only the width is variable and increases according to the rated current, starting from 50 mm/1.97 inches for smaller modules.
- The main control interface is a real time, high performance EtherCat fieldbus; the consolidated analogue/simulated encoder interface and the CANOpen interface are also available in the standard configuration. CIA 402 control modules may be used.
- Different transducers are managed as feedback from the motor; each axis module has (as standard) a resolver interface and programmable encoder, and both can be configured as the main or secondary transducer.

The resolver interface has attenuation correction, cable phase correction and amplitude gain, to improve precision in all conditions.

The encoder interface can be configured via software to read the various sensor technologies, including:

- Heidenhain EnDat 2.2 (single and absolute multi-turn) with SinCos or full digital signals
- Stegman Hiperface Encoder (single and absolute multi-turn) with SinCos signals
- SinCos encoder (with a power supply from 5 to 8 Volt)

A second optional encoder interface is available, with the same characteristics as the main interface.

- The control software architecture is designed with high-performance flexible structures, with rapid, high precision analogue/digital conversion. It can easily be customized with the aid of high-level instruments (e.g. Simulink and MatLab) to improve motor control performance, optimize accuracy of control and positioning, and to meet the needs and expectations of even the most demanding customer.
- Configuration of the control module with one or two axes. In the 2-axis configuration, the first can be the Primary and the other one the Secondary; alternatively, the two axes may be independent. From a practical viewpoint, the only difference between the Primary and the Secondary is that the HW for EtherCat and CANopen is only available in the Primary axis. With this implementation, there is just one EtherCat and CANopen node for each module, thereby reducing the number of fieldbus nodes in the system.
- The STO (Safe Torque Off) function is available on all axes with independent management for each module axis, including different feedback signal types.
- The signal and power sections are separated in the internal drive layout. This improves EMC characteristics and the rejection of electrical noise

generated by the wiring. The signals reach the upper part of the front drive panel, and the current is situated on the lower panel.

- The 24 volt auxiliary connection and power DC BUS use the same type of bus bar, to reduce the number of components and spare parts. The bus bar current may reach 250 Amps.
- The motor power connectors on the bottom have screws so that cables can be connected easily, without needing special crimping tools.
- On the bottom of the module, there is an optional interface for controlling the motor brake (2 Amp 24 Volt) one for each axis.
- There is an optional slot (X1 interface) for each axis on the front panel, for the customizable interface cards (unless it is occupied by the "second encoder" option).

#### Characteristics of the power supply module

- Centralized power supply module of the system for AC/DC conversion and DC current sharing.
- CANopen connection for internal communications and parameter configuration with PC/GUI directly from the power supply unit.
- Monitoring (via a control card with CPU) of: DC BUS voltage, three input phases, power supply module temperature, and dynamic braking commands of the drive. The information is shared amongst the various modules via CANopen.

#### GUI functions

- SW based on the Windows<sup>™</sup> operating system.
- RS232 or CANopen communication interface.
- Access to all the system variables for configuration, direct drive control, initial start-up, troubleshooting, drive monitoring, assisted axis calibration.
- The system configuration can be stored on File System and loaded in a simple, intuitive manner.
- A 4-trace oscilloscope is available for monitoring internal drive dimensions and checking performance levels. The high frequency (up to 16 KHz) data sampling method is supported by the MM C memory card.
- The oscilloscope function allows you to view analogue data from the drive in real time (e.g. resolver feedback amplitude, analogue input, output current); this is useful for the initial start-up and for troubleshooting.

#### AXIS MODULE

#### Interface



## **TECHNICAL DATA**

Single and double axis module - 50 mm/1.97 inches



Single and double axis module - 75 mm/2.95 inches





## **TECHNICAL DATA**

Single and double axis module - 100 mm/3.93 inches



Single and double axis module - 200 mm/7.87 inches



Model/Code	CC111SNN	ILNNxxxx	Nxxxx CC111ANNLNNxxxx		CC121SSN	LNxxxxx	CC112BNN	ILNNxxxx	CC122ASNLNxxxxx	
Mechanical dimensions	50 mm/1.9	50 mm/1.97 inches								
Configuration	Single	Single		Single		Double			Double	
Туре	L50A		L50A		L50A		L50B		L50B	
Module current @ 8 kHz	2		4		4		8		6	
Arms rated current	2	-	4	-	2	2	8	-	4	2
Arms peak current	4	-	8	-	4	4	16	-	8	4
Cooling	Natural						Incorporated ventilat		ion	
Weight [kg]	4,4		4,4		5,0		5,2		5,8	
Total uF capacity	135		135	135		135		135		
Connector kit code	BC7111R		BC7111R		BC7221R		BC7111R		BC7221R	
Connector kit code with brake	BC7112R		BC7112R		BC7222R		BC7222R		BC7222R	

Model/Code	CC122AANLNxxxxx CC122BSNLNxxx		ILNxxxxx	CC122BAN	ILNxxxxx	CC114CNM	ILNNxxxx	CC124BBNLNxxxxx		
Mechanical dimensions	50 mm/1.9	50 mm/1.97 inches								
Configuration	Double		Double	Double		Double			Double	
Туре	L50B		L50B		L50B		L50C		L50C	
Module current @ 8 kHz	8		10		12		16		16	
Arms rated current	4	4	8	2	8	4	16	-	8	8
Arms peak current	8	8	16	4	16	8	32	-	16	16
Cooling	Incorporate	ed ventilati	ion							
Weight [kg]	5,8		5,8		5,8		5,8		5,8	
Total uF capacity	135 135		135		135		135			
Connector kit code	BC7221R BC7221R			BC7221R		BC7113R		BC7221R		
Connector kit code with brake	BC7222R		BC7222R	BC7222R		BC7222R		BC7117R		

Model/Code	CC116DNNLNNxxxx CC116ENNLNNxxxx		ILNNxxxx	CC126CSN	ILNxxxxx	CC126CAN	ILNxxxxx	CC126CBNLNxxxxx		
Mechanical dimensions	75 mm/2.5	75 mm/2.52 inches								
Configuration	Single	Single		Single			Double		Double	
Туре	L75		L75		L75	L75			L75	
Module current @ 8 kHz	24 32		18		20		24			
Arms rated current	24	-	32	-	16	2	16	4	16	8
Arms peak current	48	-	64	-	32	4	32	8	32	16
Cooling	Incorporate	ed ventilati	ion							
Weight [kg]	6,6		6,6		7,2		7,2		7,2	
Total uF capacity	340 340		340		340		340			
Connector kit code	BC7113R BC7		BC7113R	BC7113R		BC7225R		BC7225R		
Connector kit code with brake	BC7117R		BC7117R		BC7227R		BC7227R		BC7227R	

Model/Code	CC126CCNLNxxxxx C		CC126DSNL	Nxxxxx	CC126DANLNxxxxx		CC126DBNLNxxxxx		
Mechanical dimensions	75 mm/2.52	75 mm/2.52 inches							
Configuration	Double		Double		Double		Double		
Туре	L75		L75		L75		L75		
Module current @ 8 kHz	32	2			28		32		
Arms rated current	16	16	24	2	24	4	24	8	
Arms peak current	32	32	48	4	48	8	48	16	
Cooling	Incorporated	ventilation							
Weight [kg]	7,2		7,2	7,2		7,2			
Total uF capacity	340		340	340			340		
Connector kit code	BC7225R		BC7225R		BC7225R		BC7225R		
Connector kit code with brake	BC7227R	BC7227R		BC7227R		BC7227R			

Model/Code	CC118FNNLNNxxxx CC		CC118GNN	ILNNxxxx	CC128DCN	ILNxxxxx	CC128DDNLNxxxxx		CC128ESNLNxxxxx	
Mechanical dimensions	100 mm/3.	100 mm/3.94 inches								
Configuration	Single		Single	Single			Double		Double	
Туре	L100		L100		L100		L100		L100	
Module current @ 8 kHz	48		64		40		48		34	
Arms rated current	48	-	64	-	24	16	24	24	32	2
Arms peak current	96	-	128	-	48	32	48	48	64	4
Cooling	Incorporate	ed ventilati	on							
Weight [kg]	8,0		8,0		8,6		8,6		8,6	
Total uF capacity	340 340			340		340		340		
Connector kit code	BC7113R		BC7114R		BC7225R		BC7225R		BC7225R	
Connector kit code with brake	BC7117R	BC7117R		BC7118R		BC7227R		BC7227R		

Model/Code	CC128EAN	CC128EANLNxxxxx CC128EBNLNxxxxx		CC128ECN	LNxxxxx	CC128EDN	ILNxxxxx	CC128EENLNxxxxx		
Mechanical dimensions	100 mm/3.	.00 mm/3.94 inches								
Configuration	Double		Double		Double	Double			Double	
Туре	L100		L100		L100		L100		L100	
Module current @ 8 kHz	36		40		48		56		64	
Arms rated current	32	4	32	8	32	16	32	24	32	32
Arms peak current	64	8	64	16	64	32	64	48	64	64
Cooling	Incorporate	ed ventilati	on							
Weight [kg]	8,6		8,6		8,6		8,6		8,6	
Total uF capacity	340	340		340		340		340		
Connector kit code	BC7225R BC7225R		BC7225R		BC7225R		BC7225R			
Connector kit code with brake	BC7227R		BC7227R		BC7227R		BC7227R		BC7227R	

Model/Code	CC128FSNLNxxxxx		CC128FANL	Vxxxxx	CC128FBNLNxxxxx		CC128FCNLNxxxxx		
Mechanical dimensions	100 mm/3.94	100 mm/3.94 inches							
Configuration	Double		Double	Double			Double		
Туре	L100		L100	L100			L100		
Module current @ 8 kHz	50		52		56		64		
Arms rated current	48	2	48	4	48	8	48	16	
Arms peak current	96	4	96	8	96	16	96	32	
Cooling	Incorporated	ventilation							
Weight [kg]	8,6		8,6	8,6		8,6			
Total uF capacity	340		340		340		340		
Connector kit code	BC7225R		BC7225R		BC7225R		BC7225R		
Connector kit code with brake	BC7227R		BC7227R		BC7227R		BC7227R		

Model/Code	CC130HNN	CC130HNNLNNxxxx		LNNxxxx	CC140FDNLNxxxxx		CC140FEN	LNxxxxx	CC140FFNLNxxxxx	
Mechanical dimensions	200 mm/7.	200 mm/7.87 inches								
Configuration	Single		Single		Double		Double		Double	
Туре	L200		L200		L200		L200		L200	
Module current @ 8 kHz	96		128		72		80		96	
Arms rated current	96	-	128	-	48	24	48	32	48	48
Arms peak current	192	-	256	-	96	48	96	64	96	96
Cooling	Incorporat	ed ventilati	on							
Weight [kg]	17,5		17,5	17,5		17,5		17,5		
Total uF capacity	2720		2720	2720		2720		2720		
Connector kit code	BC7115R		BC7115R		BC7225R		BC7225R		BC7225R	
Connector kit code with brake	BC7119R		BC7119R	BC7119R		BC7227R		BC7227R		

Model/Code	CC140GSNLNxxxxx		CC140GANL	Nxxxxx	CC140GBNLNxxxxx		CC140GCNL	Nxxxxx	
Mechanical dimensions	200 mm/7.87	200 mm/7.87 inches							
Configuration	Double		Double		Double		Double		
Туре	L200		L200	L200			L200		
Module current @ 8 kHz	66		68		72		80		
Arms rated current	64	2	64	64 4		8	64	16	
Arms peak current	128	4	128	8	128	16	128	32	
Cooling	Incorporated	ventilation							
Weight [kg]	17,5		17,5	17,5		17,5			
Total uF capacity	2720		2720	2720		2720			
Connector kit code	BC7226R		BC7226R	BC7226R		BC7226R			
Connector kit code with brake	BC7228R		BC7228R	BC7228R		BC7228R			

Model/Code	CC140GDNL	CC140GDNLNxxxxx CC		Nxxxxx	CC140GFNLI	Nxxxxx	CC140GGNL	Nxxxxx	
Mechanical dimensions	200 mm/7.87	200 mm/7.87 inches							
Configuration	Double		Double		Double		Double		
Туре	L200		L200	L200			L200		
Module current @ 8 kHz	88		96		112		128		
Arms rated current	64	24	64	32	64	48	64	64	
Arms peak current	128	48	128	64	128	96	128	128	
Cooling	Incorporated	ventilation							
Weight [kg]	17,5		17,5	17,5		17,5			
Total uF capacity	2720		2720		2720		2720		
Connector kit code	BC7226R		BC7226R		BC7226R		BC7226R		
Connector kit code with brake	BC7228R	BC7228R		BC7228R		BC7228R			

Further information on the drives is provided in the user manual. Note: in some modules, the current of the main axis is limited (reduced) in order to maintain the availability of the peak output current and, at the same time, to use all the rms current of the module.

#### POWER SUPPLY MODULE

#### Interface



## **TECHNICAL DATA**

Power supply module - 50 mm/1.97 inches



Power supply module 150 mm/5.90 inches



Model/Code	CC201xxxxx	CC202xxxxx			
Mechanical dimensions	50 mm/1.97 inches	150 mm/5.90 inches			
Туре	L50	L150			
Electrical line power supply	3 phases, from 65 to 528 V AC, 50/60 Hz				
Auxiliary bus bar power supply	24 V DC +/- 10%, 1 A (external supply)				
Arms rated current	54	128			
Arms peak current	130	256			
Protection	Thermal protection on the heat-sink +71°C Detection of phase loss on mains during input phase Detection of undervoltage or overvoltage				
Communication	CANopen for sharing data amongst the drives				
Cooling	Incorporated ventilation				
Weight (kg)	5,1	13,5			
Total uF capacity	1800	4500			
Connector code	BC0004R	BC0006R			

## **OPTIONS AND ACCESSORIES**

#### Motor brake options

Each axis can be fitted with an optional internal module to control the motor brake, 2 arms @ 24 V DC; its connector is located in the lower part of the drive, in front of the motor connector there is a connector for each axis in the double axis module.

#### Feedback option

Each axis can be fitted with an optional feedback module so that a second encoder channel can be used to control the machine (refer to the user manual for encoder models and configuration details); the possible modes are the same as those of the incorporated encoder, available as standard in the drive:

- SinCos, power supply from 5 to 8 Volt
- Hiperface

#### Brake resistor option

For the 50 mm power supply, there are two different brake resistors:

- DBR S standard, 15 Ohm 370 watt (supplied)
- DBR C insulated, 16 Ohm 500 watt, available as an optional extra (to be ordered separately)

For the 150mm power supply, the standard brake resistor is not supplied. The recommended resistor is 4.7 ohm/1000 watt (AR5988 to be ordered separately). In the case of application conditions with dissipated power levels higher than 1000 watt, contact the Application department to ensure the component is correctly sized.

#### **Connector kit option**

All the connectors can be ordered with a separate code. These kits are necessary for wiring the module and power supply unit, and as a spare part when repairing the wiring. For the correct coupling of the connector kit (supplied) and module, refer to the tables showing the models (on the previous pages).

Each connector kit contains:

- For the axis module: all the signal and power connector kits
- For the power supply module: the power supply connectors and brake resistor connectors (DBR)

#### Memory card option

A standard memory card slot (MMC) is available for recording, in real time, the data acquired during measurement operations.

The MMC is necessary for filing the data that may later be viewed via the GUI.

Download is via the PC-drive connection, or by removing the card and inserting it in the appropriate drive on the PC. A USB type C port for commissioning and external memory unit connection or an internal memory are available as options.

#### **ABC MODULE**

#### Auxiliary capacitor module

In the same 50mm/1.97 inch module structure, there is a capacitor module to increase braking energy capability storage.

The following table shows the total capacity of each module.

Module ID	Total cap.uF
Auxiliary capacitor module	ABC1 1800
Auxiliary capacitor module	ABC2 2700
Auxiliary capacitor module	ABC3 3600
Auxiliary capacitor module	ABC4 4500
Auxiliary capacitor module	ABC5 5400

For machines with a fast cycle and movement, the amount of energy dispersed by the brake resistor can be reduced.

At 200 cycles/min, the addition of an ABC module can save up to 3 kw in braking energy; an application note will help the machine designer to decide whether to add ABCs in the DM2020 configuration (and if so, how many).

## FILTERS

Rated voltage	From 480 V to 600 V, +10%, 50/60 Hz, at 50 °C
Ambient temperature	From -25 to +100 °C
Relative air humidity	15 - 85% (condensate not permitted)
Storage temperature	From -25 to +70 °C
IP protection rating	IP20
Acceptance test	Complies with CE
Industrial environment - EN61800-3 complies with radio screening	Permitted drive cable length - up to 100 m

Power supply model	Suitable filter codes
A	At6049, AT6059, AT6069, AT6077
L	At6048, AT6061, AT6071, AT6079

Note: to select the correct filter size for your system, please consult our application engineers.

## ENVIRONMENTAL DATA

Ambient operating temperature	From 0 to 40 °C Up to 55 °C with output current reduction (-2% / °C)
Storage temperature	From -25 to 55 °C
Transport temperature	From -25 to 70 °C
Relative humidity	1585% (condensate not permitted)
Assembly height	Up to 2,000 m AMSL (over 2,000 m AMSL with reduced current)
Certification	CE, UL, EAC
IP protection rating	IP20
Mechanical resistance in compliance with EN 60721-3-3	Vibration: 3 mm in a 2-9 Hz frequency range Vibration: 9.8 m/s2 (1g) in a 9-200 Hz frequency range Shock: 98 m/s2 (10g) at 11ms
Machine safety	STO (Safe Torque Off) SILCL3 PL"e"

## **CE MARKING**

The DM2020 servodrives comply with the low voltage directive (2014/35/CE) and EMC directive (2014/30/CE).

The "Safe Torque Off" (STO) safety function built into the drive complies with the machinery directive (2006/42/CE).

To comply with european directives, the drive meets the requisites of the relevant harmonised installation standards EN50178 (LVD), EN61800-3 (EMC) and EN 61800-5-2 (Machine Safety). The servodrives are CE-certified.

#### MODULE CODIFICATION

Version 1 E	Ctandard model	
1 E	Ctandard medal	
I E	I tandard model	
<u> </u>		
	Special model	
Mechan	ical hardware confi	guration
	Width	Pated current
value	WIGHT	(Axis 1 + Axis 2)
11	Single E0mm	( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( ) ( )
11 21		1 50A
12	Single 50mm	12 Arms
72	Double 50mm	L50B
14	Single 50mm	16 Arms
24	Double 50mm	L50C
 16	Single 75mm	32 Arms
26	Double 75mm	L75
18	Single 100mm	64 Arms
28	Double 100mm	L100
30	Single 200mm	128 Arms
40	Double 200mm	L200
	1	<u>I</u>
Axis 1 -	Currents (1)	
/alue	Rated current	Peak current
5	2 Arms	4 Arms
4	4 Arms	8 Arms
3	8 Arms	16 Arms
_	16 Arms	32 Arms
)	24 Arms	48 Arms
-	32 Arms	<u> </u>
	JZ AITIIS	64 Arms
	48 Arms	96 Arms
5	64 Arms	128 Arms
1	96 Arms	192 Arms
	128 Arms	256 Arms
	1	
xis 2 -	Currents (1)	
/alue	Rated current	Peak current
N	(2)	(2)
<u> </u>	2 Arms	4 Arms
4	4 Arms	8 Arms
3	8 Arms	16 Arms
	16 Arms	32 Arms
		40.4
J	24 Arms	48 Arms
	22.4	
Ξ	32 Arms	64 Arms
E =	32 Arms	96 Arms

<sup>(1)</sup> With a double axis configuration, the most powerful axis is indicated first

<sup>(2)</sup> Not equipped - single-axis version
<sup>(3)</sup> Standard version
<sup>(4)</sup> Values assigned by Moog

## MODULE CODIFICATION

2 E			Ч		
E	Standard mode	l			
	Special model				
Mechani	cal hardware co	nfiguration			
Value	Width	Rated current			
01	50 mm/1.97 in	54Arms/1304	Apk		
02	150 mm/5.90 in	128Arms/256	Apk		
Hardwar	e revision				
<b>Hardwar</b> Value	<b>e revision</b> Internal coding	(4)			
Hardwar Value	<b>e revision</b> Internal coding	(4)			
Hardwar Value OPT1 - S	e revision Internal coding pecial configura	(4) ations			
Hardwar Value OPT1 - S Value	e revision Internal coding pecial configura Version	( <sup>4</sup> ) ations			
Hardwar Value OPT1 - S Value 00	<b>e revision</b> Internal coding <b>pecial configura</b> Version Standard	( <sup>4</sup> ) ations			
Hardwar Value OPT1 - S Value 00	<b>e revision</b> Internal coding <b>pecial configura</b> Version Standard <b>pecial configura</b>	( <sup>4</sup> ) ations			
Hardwar Value OPT1 - S Value 00 OPT2 - S Value	e revision Internal coding pecial configura Version Standard Pecial configura Version	( <sup>4</sup> ) ations ations			
Hardwar Value OPT1 - S Value 00 OPT2 - S Value 00	e revision Internal coding pecial configura Version Standard Pecial configura Version Standard	( <sup>4</sup> ) ations ations			
Hardwar Value OPT1 - S Value 00 OPT2 - S Value 00 04	e revision Internal coding pecial configura Version Standard Pecial configura Version Standard Extended BUS ( External Soft S	(4) ations ations CAPS and tart Resistor ( <sup>5</sup> )			

# OTHER MOOG PRODUCT OFFERING

We are committed to offering a range of servo motor products with matched servo drives that are easy to integrate into industrial applications.

Moog servo motors are electronically commutated synchronous AC motors with magnet field excitation. Our portfolio includes three motor families, with different characteristics to answer to any applicative need.

#### CD (Compact Dynamic) Brushless Servo Motors

Combining compactness with performance, the CD servo motor series offers one of the industry's widest power ranges with continuous nominal torques from 0.15 to 77 Nm (1.3 to 681 lb-in). The modular design is supported by a variety of options with

Moog's application engineers capable of supplying fully customized solutions.



#### HD (High Dynamic) Brushless Servo Motors

The HD servo motor series stands out for its extremely high level of dynamic and high acceleration speeds. With nominal torques from 2 Nm to 909 Nm (20 to 8047 lb-in) and a fully customizable modular structure,

these motors are perfect for high dynamic applications where reliable performance is fundamental.



#### ExD (Explosion-Proof) Brushless Servo Motors

Designed and tested for operation in conditions where vapors or gases form flammable or explosive environments.

Flameproof housing withstands internal explosions without bursting.



#### CP (Compact Power) Brushless Servo Motors

The CP servo motor series is a range of compact motors with high power density. These motors are designed for dynamic

servo applications where small dimensions (especially shorter length) and high torque are needed.



# OTHER DRIVE PRODUCTS

Moog servo drives and electronic products can deliver the highest level of control accuracy, dynamic performance and reliability in both centralized and decentralized configurations. Machine designers are allowed complete freedom to achieve their goals, with space savings and optimized layouts perfectly fitting both traditional cabinets and distributed control architectures.

## **CENTRALIZED SOLUTIONS**

Moog drive portfolio for cabinet installation include both single-axis and multi-axis configurations.

#### DM2020 Series Ultra Compact Single-Axis Servo Drive

Standalone servo drive with integrated power supply, specifically designed with extremely compact dimensions for space saving.



## **DECENTRALIZED SOLUTIONS**

Out-of-cabinet products for flexible machine architecture.

#### DR2020 Machine-Mounted Servo Drive

On-board servo control, for installation on machine surfaces and easy daisy-chain and out of the cabinet connections.

#### DI2020 Motor Integrated Servo Drive

Servo control integrated with a high efficiency brushless motor. It allows

great machine design freedom and a significant reduction in wiring and cabinet space.



## SmartMotor™

Highly programmable, integrated servo motor systems with an encoder, an

amplifier, a controller, RS-232/RS-485 communication, and IOs. Ideal for fast, high precision applications.



# MORE PRODUCTS. MORE SUPPORT.

Moog covers an extensive range of motion control solutions and also provides service and support. Moog has offices around the world. For more information or the office nearest you, visit **www.moog.com/contact-us/moog-facilities** 

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South Africa

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#### For product information, visit **www.moog.com** or email us **em-motioncontrol@moog.com**

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WHEN PERFORMANCE REALLY MATTERS